# EELE 250: Circuits, Devices, and Motors

**Electric Motors** 

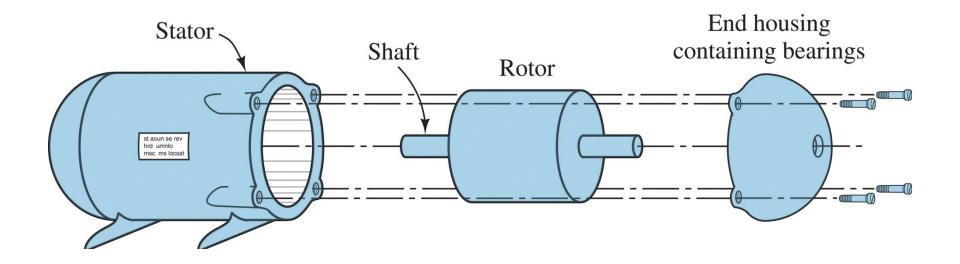
#### Assignment Reminder

- Read 16.1 16.3
- No quiz this week.
- Practice problems assigned soon.
- Work on Lab #9 this week. This is the last lab!

# **Motor Principles**

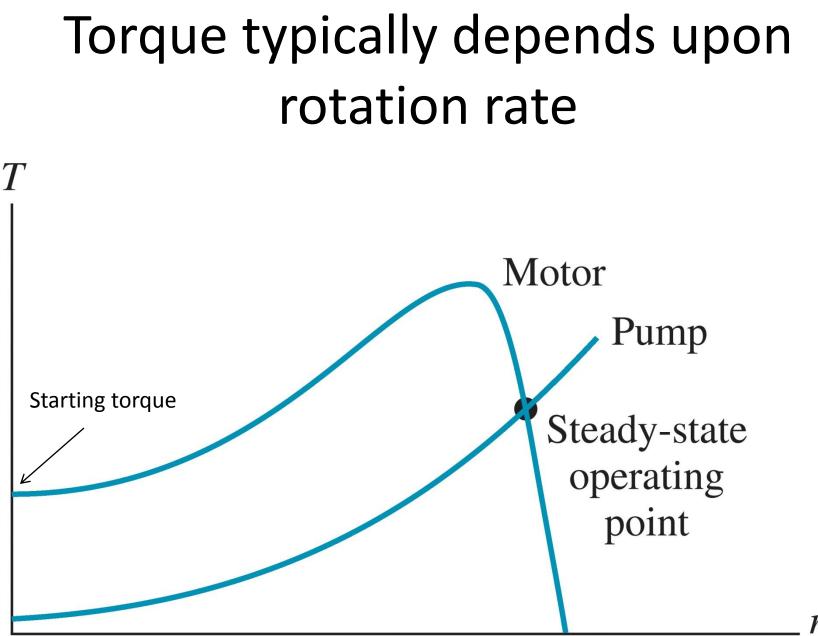
- Electric current in a magnetic field produces a force
- Magnetic field may be from a permanent magnet or from an electromagnet
- Conductor loops are used to increase effective length of current in the magnetic field
- Motors may run on AC or DC
- Various electric motor designs are possible

#### **Electrical Motors**



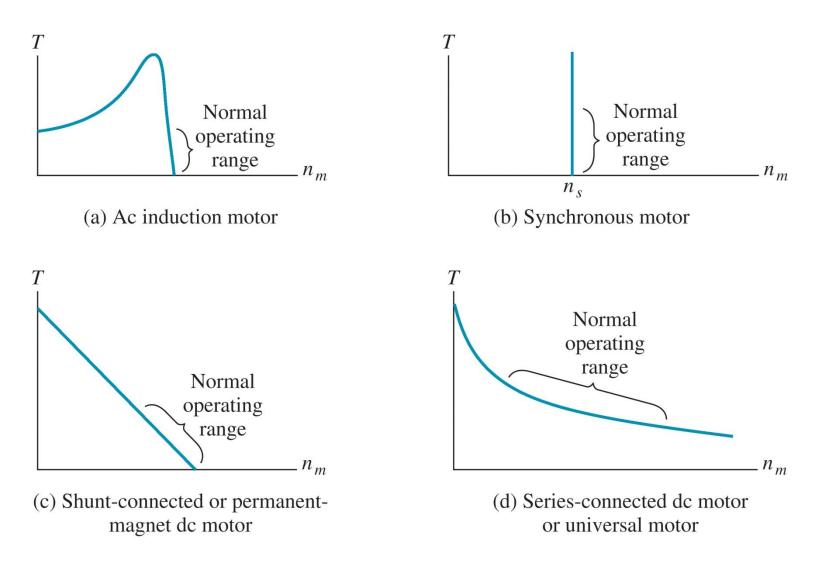
### Torque

- Most useful electric motors produce rotational force: they "twist" a shaft
- Torque is the tendency of a force to rotate an object about an axis
- Newton-meter is the SI unit of torque
- For a shaft, the torque is the product of the tangential force and the radial lever arm length: T = F x r



 $n_m$ 

#### Torque vs. speed for several motor types



#### **Motor Properties**

- Power input, 3-phase:  $\sqrt{3} V_{rms} I_{rms} cos(\theta)$  [watts]
- Rotation rate:  $\omega_m$  [rad/sec] =  $2\pi n_m/60$
- Power output:  $T_{out} \omega_m$  [watts]
- (1 horsepower = 746 watts)
- Efficiency =  $(P_{out}/P_{in}) \times 100\%$
- Speed regulation:  $(n_{no-load} n_{full-load})/n_{full-load}$

## Example

- 3-phase AC induction motor rated 5-hp, attached to 440 V<sub>rms</sub> line source.
- When at <u>rated full-load</u> condition, current is 6.8 A rms, power factor is 78% (lagging), and speed is 1150 rpm.
- With <u>no load</u>, current becomes 1.2 A rms, power factor 30% (lagging), and speed is 1195 rpm
- Find efficiency, power loss at full load, input power with no load, and the speed regulation

# Example (cont.)

- 5-hp = 5 x 746 W = 3.73 kW
- Pin =  $\sqrt{3} V_{rms} I_{rms} \cos(\theta) = \sqrt{3.440.6.8.0.78}$ = 4.042 kW
- Ploss = Pin Pout = 4.042 kW 3.73 kW
  = 312 W
- Full-load efficiency = (3.73 kW)/(4.042 kW)
  = 92.3 %
- Speed regulation = (1195-1150)/1150 = 3.9%